1.0 Overview

Watch Dog Timer (WDOG) provides a way to recover from software malfunctions by applying a reset to the system. The reset is a warm reset—the microcontroller starts execution at address 0 in Thread Mode (normal mode).

Figure 1 shows the basic diagram of a WDOG timer.

![Figure 1: WDOG timer basic diagram](image)

The watch dog begins counting down from the WDOGLOAD register value, and will be reloaded by writing to the interrupt clear register (WDOGINTCLR). If the timer counts down to 0 twice, than the WDOGRES signal will be asserted, causing a reset to the system. Optionally, in Window mode, if the counter value is higher than the Window register value, than the WDOGRES will be asserted causing a reset to the system.
Figure 2 shows the WDOG time-out and Window mode reset.

![Graph showing WDOG time-out and Window reset](image)

**Figure 2: WDOG Time out or Window reset**

### 2.0 Application Note Layout

This application note (AN) provides a brief description of the WDOG unit’s memory map, configuration and programming.

### 3.0 WDOG Unit Hardware

The WDOG Unit is mapped to the memory region from 0x4000_8000 to 0x4000_8FFF. It has 8 registers. For more information on each register, refer to Chapter 11 of the UT32R500 Functional Manual.
3.1 **WDOG Load Register**

The WDOG Load Register (WDOGLOAD) contains the reload value to count down from. When the counter times out twice, the WDOGRES signal will be asserted, resetting the system.

3.2 **WDOG Control Register**

The Control Register (CTRLREG) enables reset by setting reset enable, bit [1], to 1; the Window reset enable (optional), bit[2], to 1; the interrupt enable, bit [0], to 1.

3.3 **WDOG Interrupt Clear Register**

The WDOG Interrupt Clear Register (WDOGINTCLR) accepts the specific value **0x1357c0b1** to clear the watchdog interrupt and reload the timer from the value in WDOGLOAD.

3.3.1 **WDOG Window Value Register**

The WDOG Window Register (WDOGWINDOW) holds the value compared to by the timer, and if the timer’s value is greater, than the WDOGRES signal will be asserted, causing a reset to the system.

3.3.2 **WDOG Lock Register**

The WDOG Lock Register (WDOGLOCK) locks write access to load, control, and window value registers by setting WDOGLOCK, bit [0], to 1.
4.0 **WDOG Initialization**

The watch dog time out period of 5 seconds for the example application is given by:

\[
\text{Time out} = \text{pclk} \times \text{LoadValue} \\
\text{Time out} = 20\text{ns} \times 250000000 \\
\text{Time out} = 5 \text{ seconds}
\]

Code 1 initializes the WDOG timer for reset and interrupt enable with the time out set to 5 seconds, and for specifics on the API’s, refer to Wolv_StdPeriph_Lib at [www.cobham.com](http://www.cobham.com).

```c
WDOG_StructInit (&WDOG_InitStruct);

// PCLK=50Mhz, 20ns
// Period = 20ns * LoadValue; LoadValue = Period/20ns=5s/20ns=500000000
WDOG_InitStruct.LoadValue = 250000000;

// Init the watchdog
WDOG_Init (WDOG, &WDOG_InitStruct);
WDOG_Cmd (WDOG, ENABLE);

// WDOG_IntConfig (WATCHDOG_TypeDef *WDOGx, EnableState WindowResetEnable, 
// EnableState ResetEnable, EnableState InterruptEnable) 
// Enable reset and interrupt, Window reset disabled for now
WDOG_IntConfig (WDOG, DISABLE, ENABLE, ENABLE);
```

**Code 1: WDOG Timer Initialization**
5.0  **WDOG Unit Programming**

Section 3.0 presented some of the basic configurations for the WDOG core unit. The following section show programming examples by making use of Cobham API’s for the UT32RM0R500.

Putting it all together, Code 2 shows the main subroutine for “kicking the dog” and an endless loop for testing the WDOG timer reset functionality.

```c
int main (void){
    // Initialization and settings from previous sections go here.
    for(;;){
        if(SysTickExpired)
        {
            SysTickExpired=0;
            // Infinite loop to test the watch dog (WDOG) reset.
            while(1);
        }
        // Kick the dog!
        WDOG_PetTheDog (WDOG);
    }
}

void SysTick_Handler(void){
    SysTickExpired=1;
    GPIO_WriteOutputDataBit (GPIO2, PIN_13, SET);// LED on
    __ASM volatile ("nop");
    GPIO_WriteOutputDataBit (GPIO2, PIN_13, RESET);// LED off
}
```

**Code 2: Sample program for testing WDOG reset**
Figure 3 shows an Oscilloscope plot for the process running and the WDOG timer, timing out after 5 seconds and resetting the system.

![Oscilloscope plot]

**Figure 3: WDOG 5 secs time out reset**

6.0  **Summary and Conclusion**

For unexpected and unknown software behaviors, the Watch Dog Timer (WDOG) provides a way to recover from them by applying a reset to the system and rebooting it to its normal state.

For more information about our UT32M0R500 microcontroller and other products, please visit our website: [www.cobham.com/HiRel](http://www.cobham.com/HiRel) or email us at info-ams@cobham.com.
## REVISION HISTORY

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